1st Half Review & Mid-term Guideline

Topics

- Introduction to machine learning
- Linear algebra, calculus and probability theorem
- K nearest neighbors
- Linear regression
- Naïve Bayes
- Logistic regression

Introduction to machine learning

Types of Learning Task

Supervised learning

Training data includes desired outputs

Unsupervised learning

Training data does not include desired outputs

Semi-supervised learning

Training data includes a few desired outputs

Self-supervised learning

Training data contains supervised signals extracted from the data itself

Reinforcement learning

Rewards from sequence of actions

Supervised Learning

- Given examples of a function (X, Y=F(X))
- Predict function F(X) for new examples X
 - Discrete Y: Classification
 - Continuous Y: Regression

Preliminaries

Basic Vector Operations

$$\mathbf{x} + \mathbf{y} = (x_1, x_2) + (y_1, y_2) = (x_1 + y_1, x_2 + y_2)$$

$$a\mathbf{v} = a(x_1, x_2) = (ax_1, ax_2)$$

$$\boldsymbol{x} \cdot \boldsymbol{y} = x_1 y_1 + x_2 y_2$$

Matrix Times Matrix

$$L = M \cdot N$$

$$\begin{bmatrix} l_{11} & l_{12} & l_{13} \\ l_{21} & l_{22} & l_{23} \\ l_{31} & l_{32} & l_{33} \end{bmatrix} = \begin{bmatrix} m_{11} & m_{12} & m_{13} \\ m_{21} & m_{22} & m_{23} \\ m_{31} & m_{32} & m_{33} \end{bmatrix} \cdot \begin{bmatrix} n_{11} & n_{12} & n_{13} \\ n_{21} & n_{22} & n_{23} \\ n_{31} & n_{32} & n_{33} \end{bmatrix}$$

$$l_{12} = m_{11}n_{12} + m_{12}n_{22} + m_{13}n_{32}$$

Multiplication

• Is AB = BA? Maybe, but maybe not!

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ae + bg & \dots \\ \dots & \dots \end{bmatrix} \quad \begin{bmatrix} e & f \\ g & h \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} ea + fc & \dots \\ \dots & \dots \end{bmatrix}$$

- Heads up: multiplication is NOT commutative!
- Identity matrix:

$$AI = IA = A$$

- Multiplication is associative:
- (A*B)*C=A*(B*C)

Chain Rule

- Help us to compute derivatives for composite functions.
- Three variables: z, y, x.

Three variables:
$$z, y, x$$
.
• $z = f(y), y = g(x)$

$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx} = f'(g(x))g'(x)$$

Bayes' Theorem

- Joint probability P(A = a, B = b): The probability that A = a and B = b happen simultaneously.
- Conditional probability $P(B=b|A=a)=\frac{P(A=a,B=b)}{P(A=a)}$: The probability of B=b, provided that A=a has occurred.
- Marginalization: $P(B) = \sum_{A} P(A, B)$
- Bayes' theorem:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

K nearest neighbors

k-nearest neighbors

- Find the k-nearest neighbors to $x^{(new)}$ in the data
 - i.e., rank the feature vectors according to Euclidean distance
 - select the k vectors which are have smallest distance to $x^{(new)}$
- Regression
 - Usually just average the y-values of the k closest training examples
- Classification
 - ranking yields k feature vectors and a set of k class labels
 - pick the class label which is most common in this set ("vote")
 - Note: for two-class problems, if k is odd ($k=1,3,5,\ldots$) there will never be any "ties"

Pitfalls: computational cost

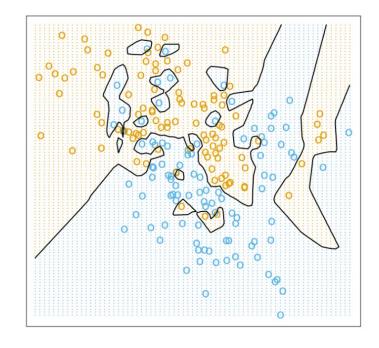
- Number of computations at training time: 0
- Number of computations at test time, per query (naïve algorithm)
 - Calculate m-dimensional Euclidean distances with n data points: O(mn)
 - Sort the distances: $O(n \log n)$
- This must be done for each query, which is very expensive by the standards of a learning algorithm!
- Need to store the entire dataset in memory!
- Tons of work has gone into algorithms and data structures for efficient nearest neighbors with high dimensions and/or large datasets.

k-nearest neighbors

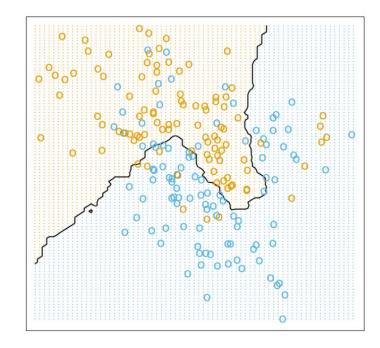
- Tradeoffs in choosing k
 - Small k
 - Good at capturing fine-grained patterns
 - May overfit, i.e. be sensitive to random idiosyncrasies in the training data
 - Large *k*
 - Makes stable predictions by averaging over lots of examples
 - May underfit, i.e. fail to capture important regularities
 - Rule of thumb: $k < \sqrt{n}$, where n is the number of training examples

k-nearest neighbors





$$k = 15$$



Linear Regression

Linear regression

n features

•
$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$

- Define "feature" $x_0 = 1$, then
- $h_{\theta}(x) = \theta^T x$

$$\theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \cdots \\ \theta_n \end{pmatrix} \qquad x = \begin{pmatrix} 1 \\ x_1 \\ \cdots \\ x_n \end{pmatrix}$$

Linear regression

Normal equation

$$\theta = (X^T X)^{-1} X^T y$$

$$y = \begin{pmatrix} y^{(1)} \\ \dots \\ y^{(m)} \end{pmatrix}$$

$$\theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \cdots \\ \theta_n \end{pmatrix}$$

$$y = \begin{pmatrix} y^{(1)} \\ \cdots \\ y^{(m)} \end{pmatrix} \qquad \theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \cdots \\ \theta_n \end{pmatrix} \qquad X = \begin{pmatrix} x_0^{(1)} & \cdots & x_n^{(1)} \\ \vdots & \ddots & \vdots \\ x_0^{(m)} & \cdots & x_n^{(m)} \end{pmatrix}$$

Example

Size (feet ²)	Number of bedrooms	Number of floors	Age of home (years)	Price (\$1000)
x_1	x_2	x_3	x_4	y
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

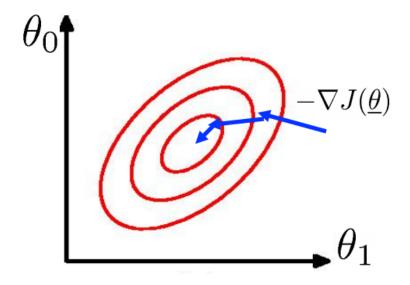
$$X = \begin{pmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{pmatrix}$$

$$y = \begin{pmatrix} 460 \\ 232 \\ 315 \\ 178 \end{pmatrix}$$

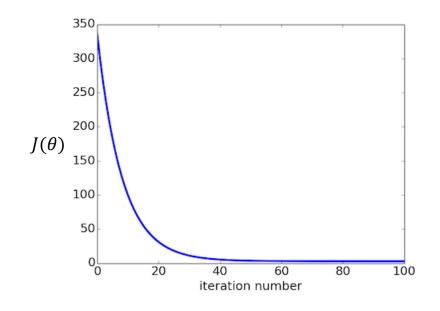
Linear regression

Gradient descent

•
$$\nabla J(\theta) = \left(\frac{\partial J(\theta)}{\partial \theta_0}, \frac{\partial J(\theta)}{\partial \theta_1}, \cdots\right)$$



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Initialize \theta
Do {
\theta \leftarrow \theta - \alpha \nabla J(\theta)
} while (stop condition)
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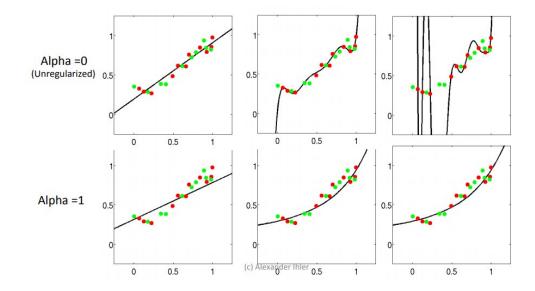


Regularization for preventing overfitting

• Modify loss function to add "preference" for small parameter values

$$J(\boldsymbol{\theta}) = \sum_{i=1}^{\infty} (y^{(i)} - \boldsymbol{\theta}^T \boldsymbol{x}^{(i)})^2 + \frac{\alpha}{2} \|\boldsymbol{\theta}\|$$

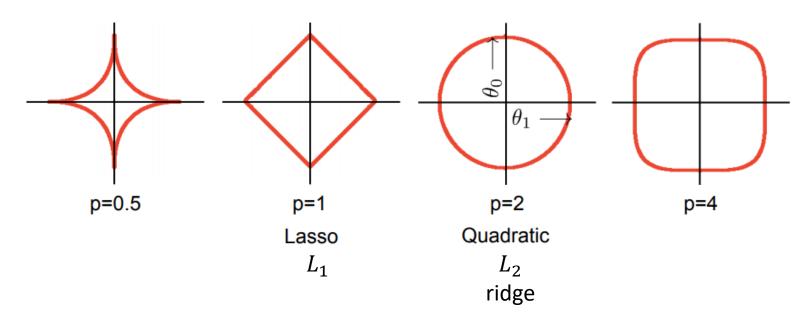
Compare between unreg. & reg. results



Different regularization functions

• More general, L_p regularizer: $\left(\sum_j \left|\theta_j\right|^p\right)^{\frac{1}{p}}$

Isosurfaces: $\|\theta\|_{p} = constant$



Naïve Bayes Classifier

Bayes classifier: Naïve Bayes

- Estimate p(y) = [p(y=0), p(y=1)...]
- Estimate p(x | y=c) for each class c
- Calculate p(y=c | x) using Bayes rule

$$\Rightarrow p(y|x) = p(x|y)p(y)/p(x)$$

• Choose the most likely class c

$$= \frac{p(x|y)p(y)}{\sum_{c} p(x|y=c)p(y=c)}$$

• Naïve Bayes: $p(x \mid y=c) = \prod_i p(x_i \mid y=c)$

Example: Naïve Bayes

Observed Data:

X ₂	У			
1	0			
0	0			
0	1			
0	0			
1	1			
1	0			
0	1			
0	1			
	1 0 0 0 1 1			

$$\hat{p}(y=1) = \frac{4}{8} = (1 - \hat{p}(y=0))$$

$$\hat{p}(x_1, x_2 | y = 0) = \hat{p}(x_1 | y = 0) \,\hat{p}(x_2 | y = 0)$$

$$\hat{p}(x_1 = 1|y = 0) = \frac{3}{4}$$
 $\hat{p}(x_1 = 1|y = 1) = \frac{2}{4}$
 $\hat{p}(x_2 = 1|y = 0) = \frac{2}{4}$ $\hat{p}(x_2 = 1|y = 1) = \frac{1}{4}$

$$\hat{p}(y=1|x_1=1,x_2=1) = \frac{\frac{4}{8} \times \frac{2}{4} \times \frac{1}{4}}{\frac{3}{4} \times \frac{2}{4} \times \frac{4}{8} + \frac{2}{4} \times \frac{1}{4} \times \frac{4}{8}}$$

$$= \frac{1}{4}$$

Logistic Regression

Linear classifier

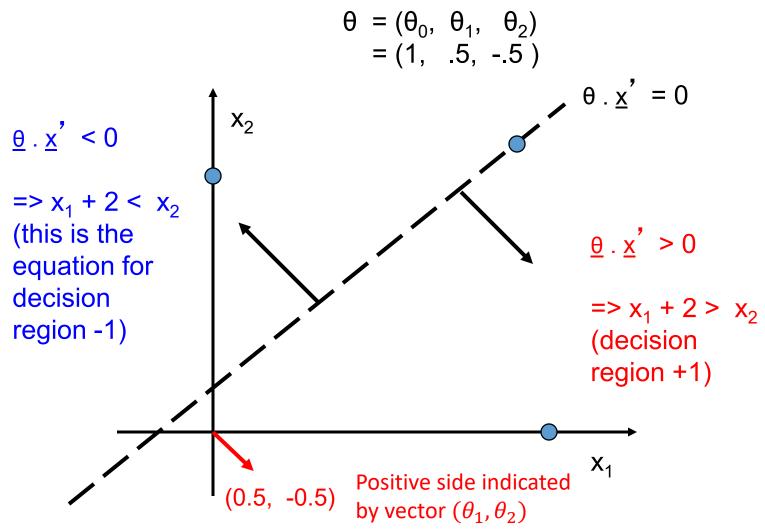
Representation

$$\hat{y} = T(\theta \cdot x)$$

Decision boundary

$$\theta \cdot x = 0$$

Linear Decision Boundary



From P. Smyth

Logistic regression classifier

0.5

Use logistic/sigmoid function

$$h_{\theta}(x) = \sigma(\theta x) = \frac{1}{1 + e^{-\theta x}}$$

- Interpret $\sigma(\theta x)$ as a probability that y=1
- Use a negative log-likelihood loss function
 - If y = 1, cost is $-\log \Pr[y=1] = -\log \sigma(\theta x)$
 - If y = 0, cost is $-\log \Pr[y=0] = -\log (1 \sigma(\theta x))$
- Can write this succinctly:

$$J(\underline{\theta}) = -\frac{1}{m} \Big(\sum_{i} y^{(i)} \log \sigma(\theta \cdot x^{(i)}) + (1 - y^{(i)}) \log(1 - \sigma(\theta \cdot x^{(i)})) \Big)$$
Nonzero only if y=1
Nonzero only if y=0